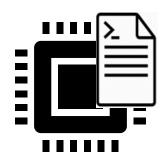
Verifying Safety and Accuracy of Approximate Parallel Programs via Canonical Sequentialization

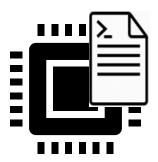
Vimuth Fernando, Keyur Joshi, Sasa Misailovic University of Illinois at Urbana-Champaign

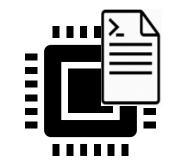




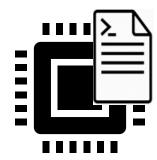


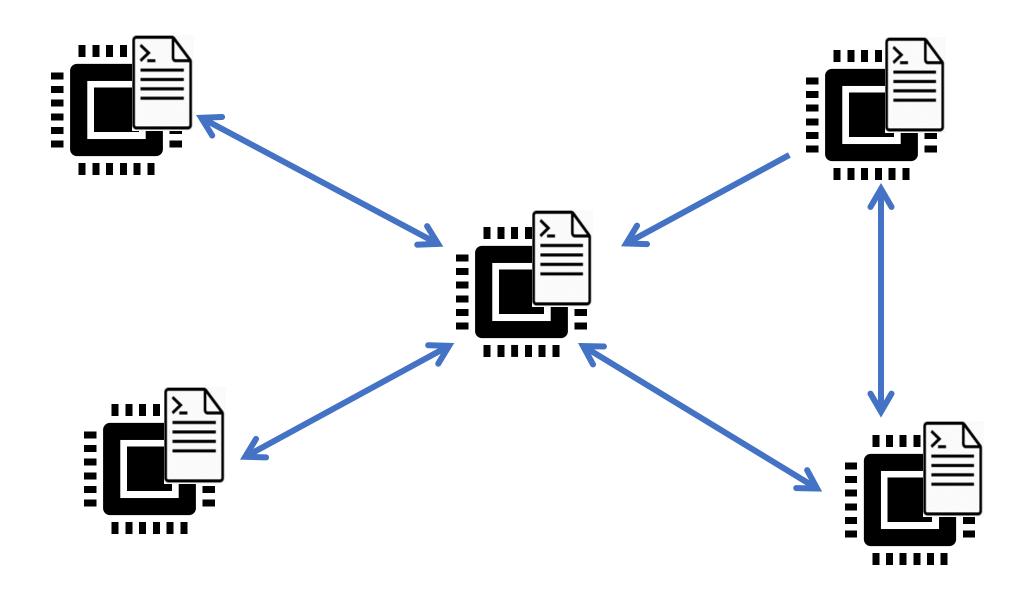


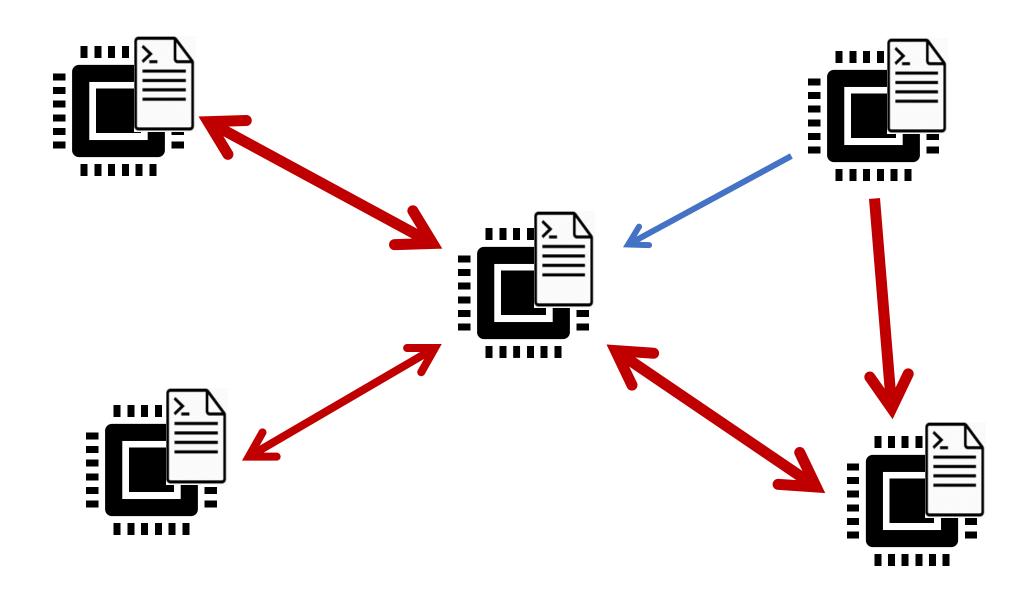


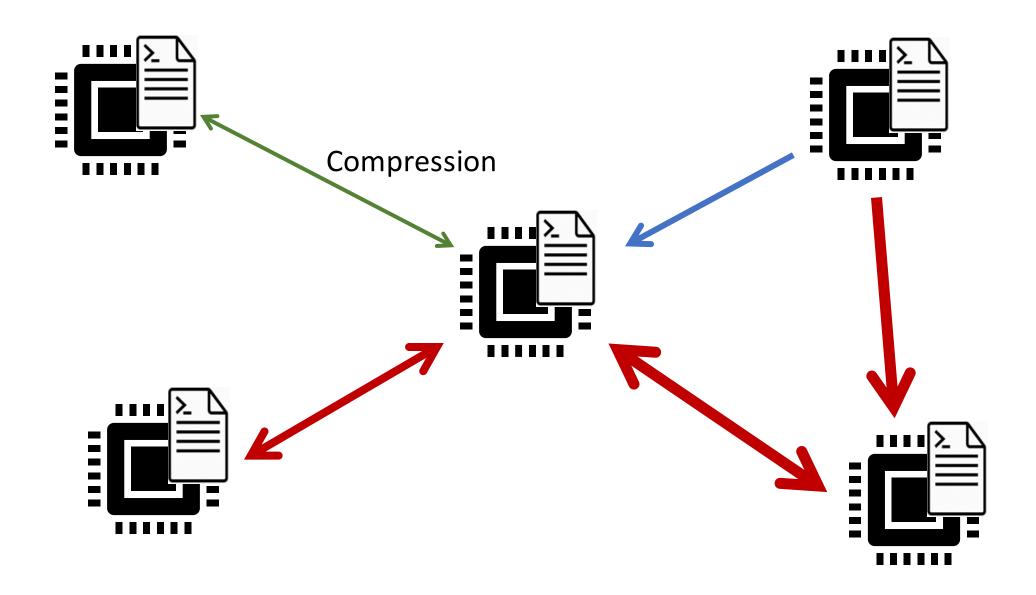


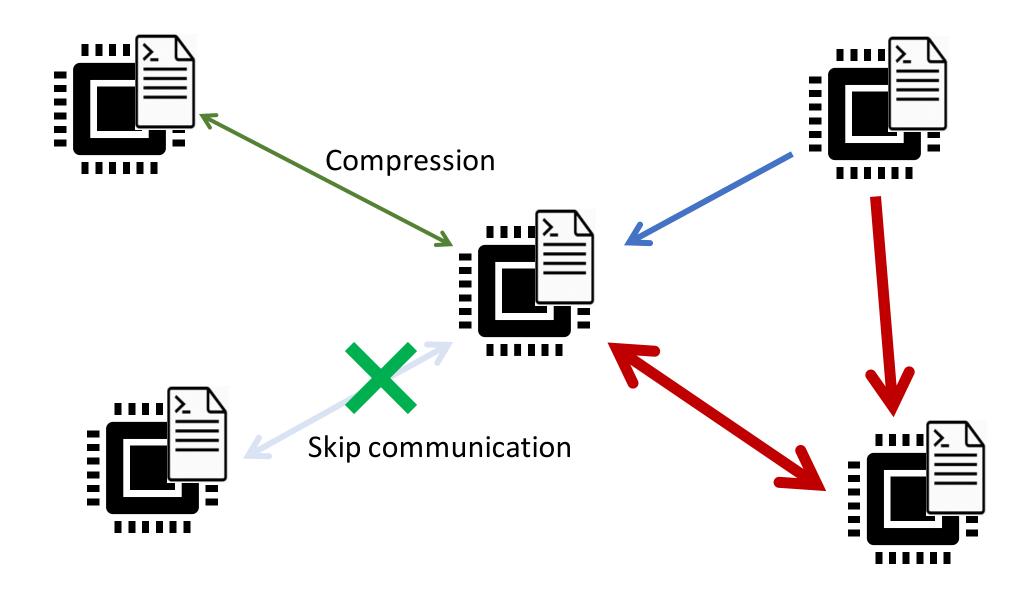


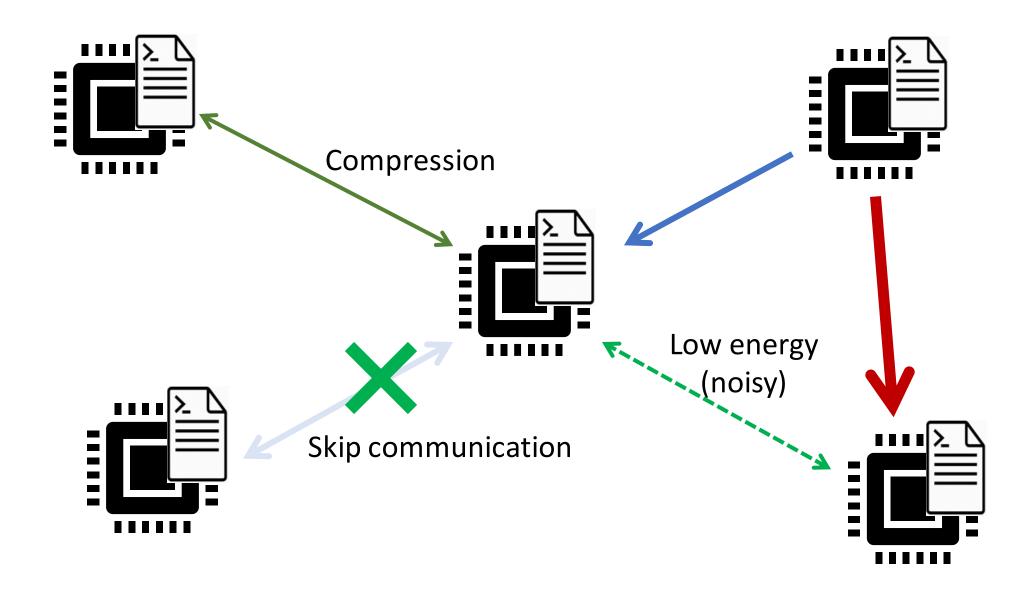










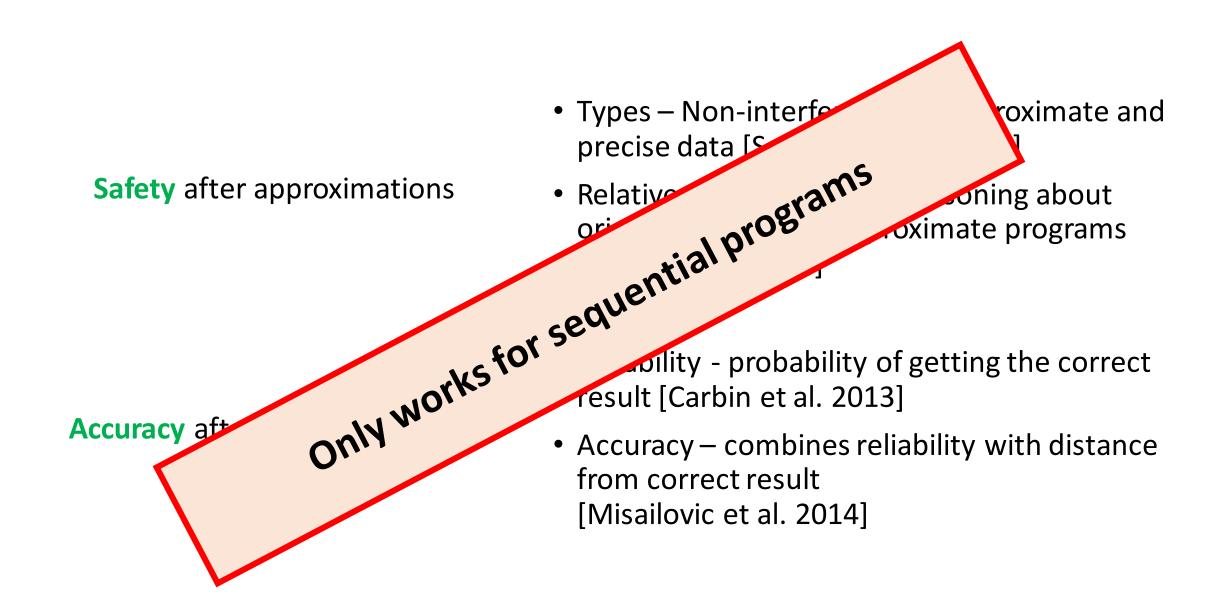


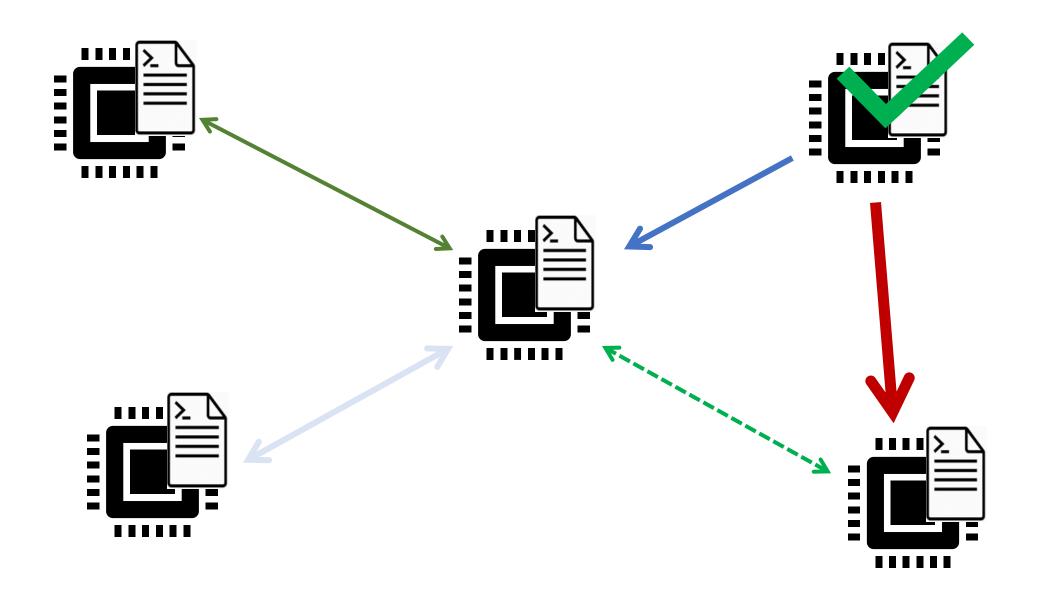
How safe is the program?

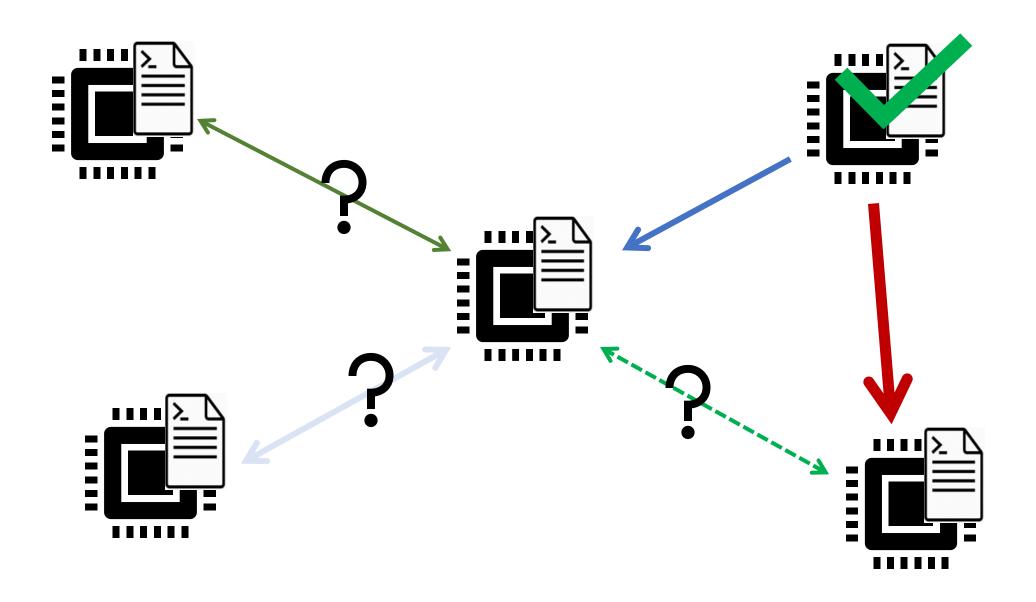
Approximate program should not crash, get stuck, or produce unacceptable results

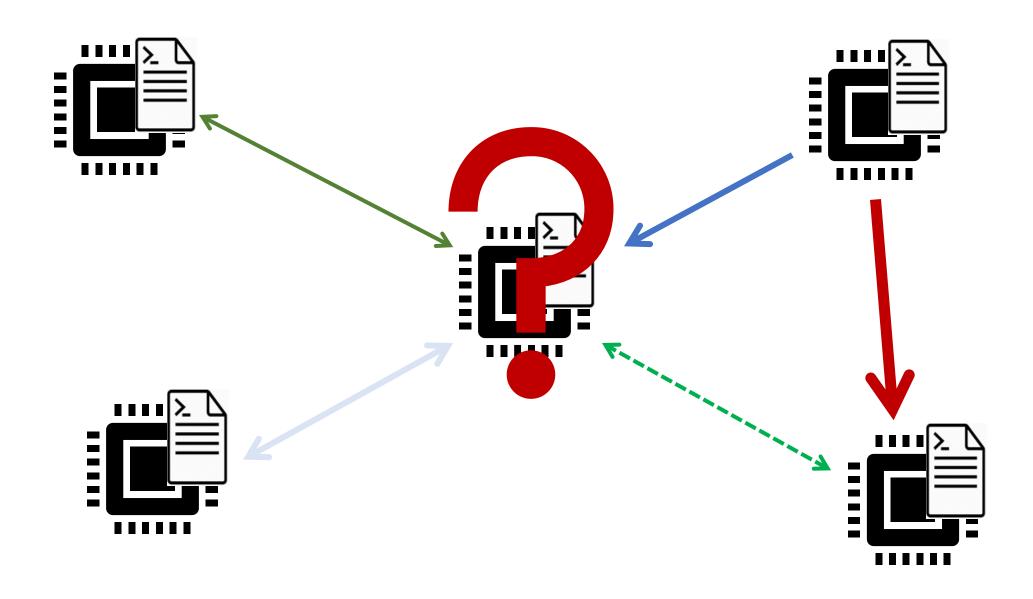
How accurate are the results?

Approximate program should produce results with acceptable accuracy/ reliability





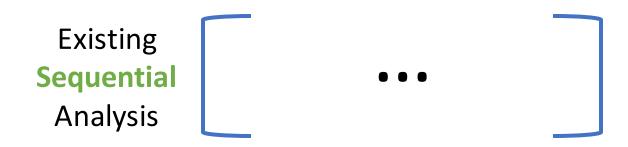


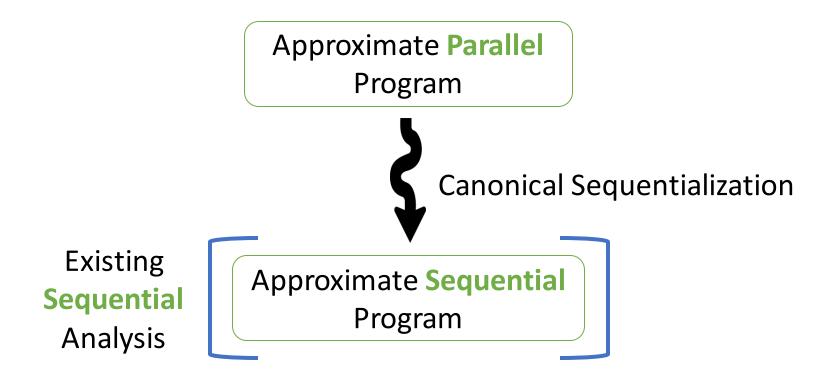


How do we proceed?

- Completely new versions of all analyses?
- Types Non-interference of approximate and precise data [Sampson et al. 2011]
- Relative safety Transfer reasoning about original program to approximate programs [Carbin et al. 2012]
- Reliability probability of getting the correct result [Carbin et al. 2013]
- Accuracy combines reliability with distance from correct result [Misailovic et al. 2014]

Approximate **Parallel** Program

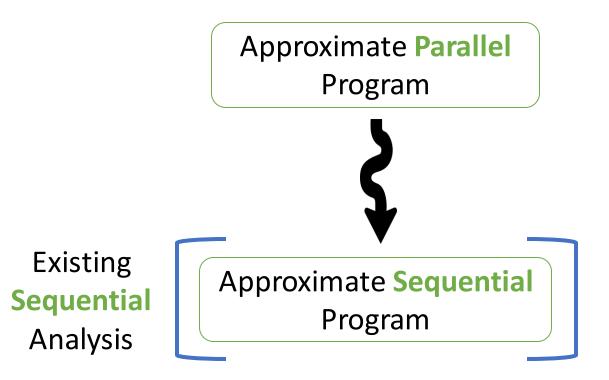




How do we express parallel approximations?

How to enforce and verify safety/accuracy properties?

Under what conditions will the existing analyses apply?



Parallely!

Language with support for modeling parallel approximations

- Software-level approximation
- Environment-level noise

Verification of safety and accuracy using canonical sequentialization

- Type-safety (Non-Interference)
- Deadlock-freeness
- Relative safety
- Reliability
- Accuracy
- And more

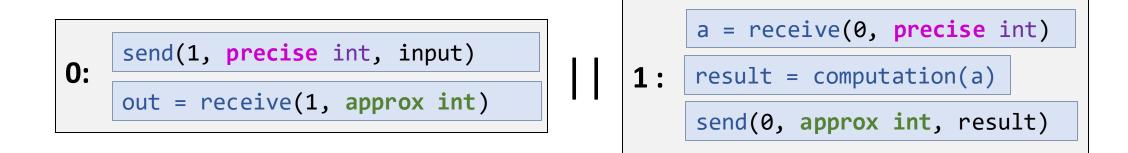
Asynchronous distributed message passing processes

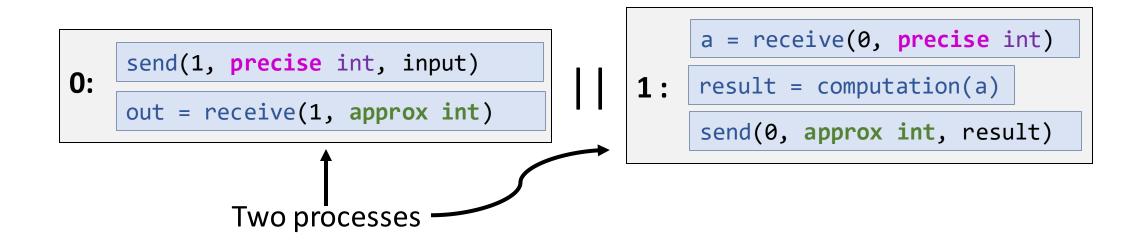
Two types of data : precise and approx.

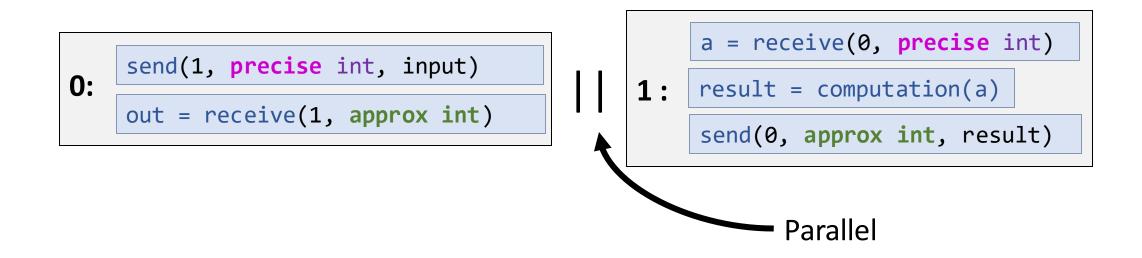
Communicates through typed channels

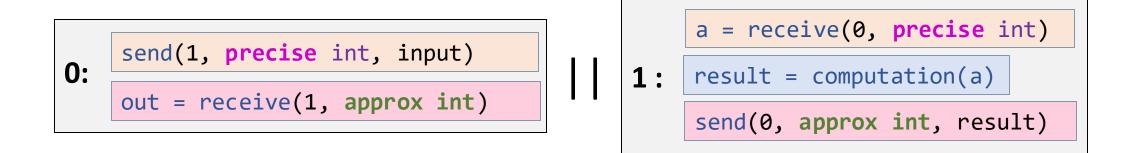
0: send(1, precise int, input)
 out = receive(1, approx int)

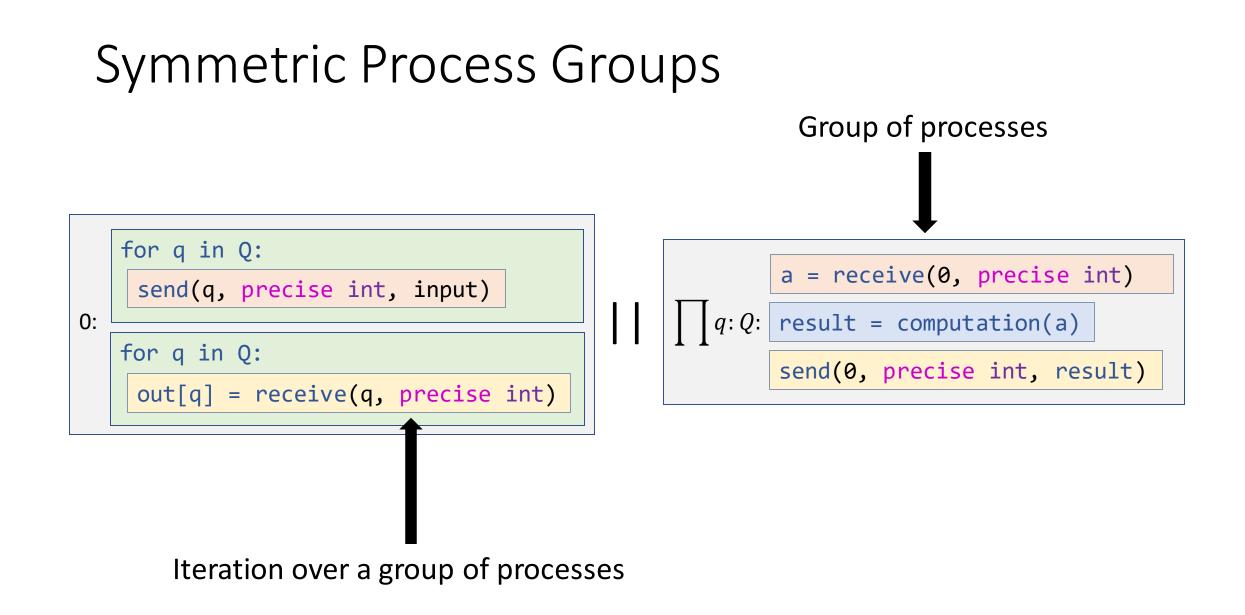
a = receive(0, precise int)
1: result = computation(a)
send(0, approx int, result)









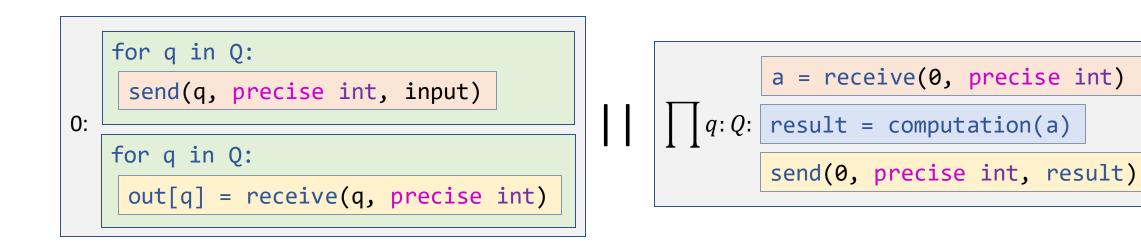


Symmetric Non-determinism

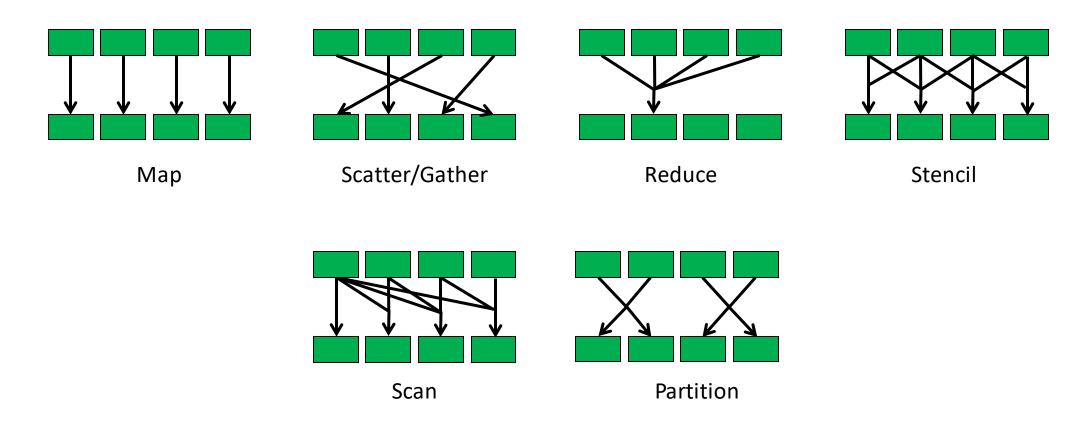
All receive statements have a unique matching send statement

[Bakst et al. OOPSLA 2017]

Map-Reduce Pattern

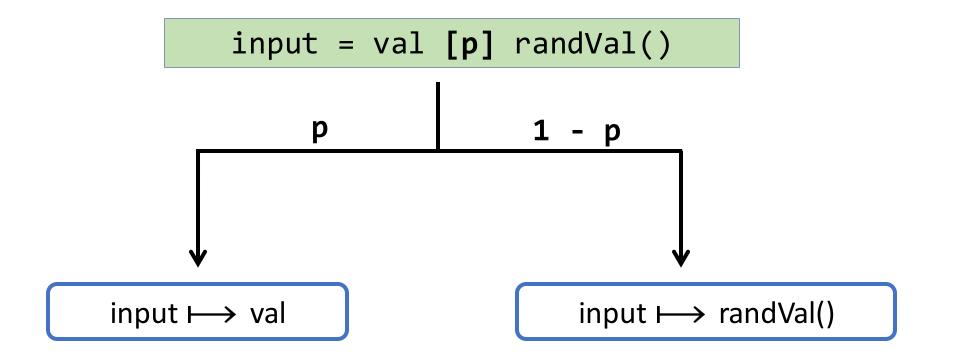


Communication Patterns easily expressible in Parallely



Covers all the patterns in [M. Samadi, D. A. Jamshidi, J. Lee, and S. Mahlke. 2014. Paraprox: Pattern-based Approximation for Data Parallel Applications. In ASPLOS.]

Approximation Primitives- Probabilistic Choice



Approximation Primitives- Probabilistic Choice

input = val **[p]** randVal()

• Low energy channels that may corrupt the data being transmitted

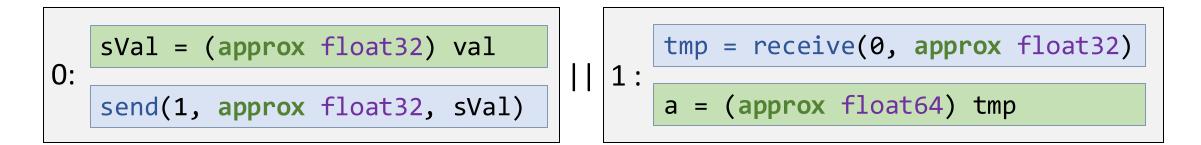
1: a = receive(0, approx int)

Approximation Primitives- Precision Conversion

 Casting to reducing the precision of data that has primitive numeric types

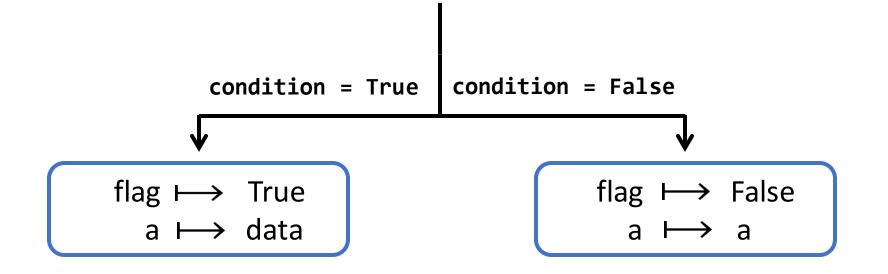
sVal = (approx float32) val

• Communicate in low precision



Approximation Primitives – Conditional Communication

0: cond-send(condition, 1, approx int, data)



Approximation Primitives – Conditional Communication

0: cond-send(condition, 1, approx int, data)

1: flag, a = cond-receive(0, approx int)

• Skip sending some data

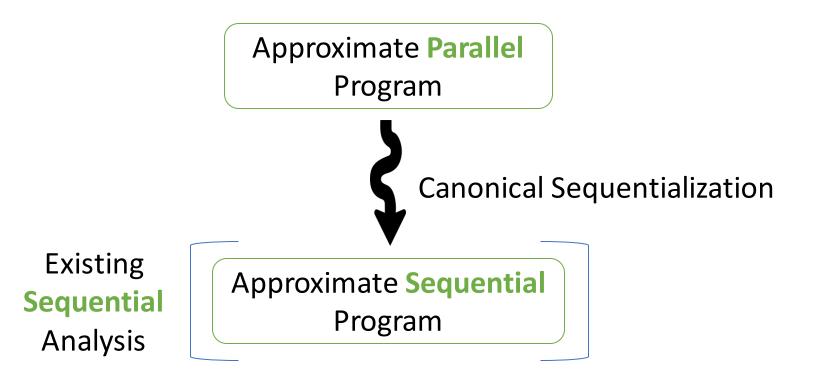
0: skip = 1 [0.99] 0
cond-send(skip, 1, approx int, data)
[] 1: flag, a = cond-receive(0, approx int)

What approximations can be modelled with Parallely

- Failing tasks
- Noisy channel
- Precision reduction
- Memoization
- Approximate reduce
- Loop perforation

- probabilistic-choice + conditional communication
- probabilistic-choice
- casting
- probabilistic-choice + conditional communication
- probabilistic-choice + conditional communication
- probabilistic-choice

How do we analyze Parallely programs?



Canonical Sequentialization (Bakst et al. OOPSLA 2017)

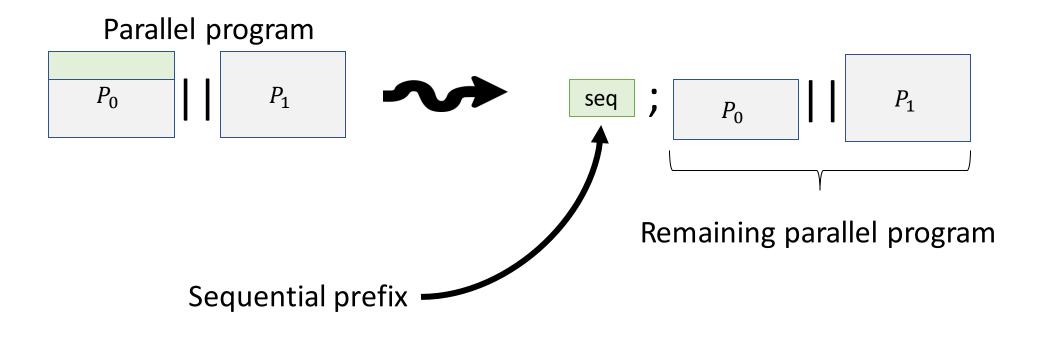
Generate an equivalent sequential program using rewriting

Works for programs with symmetric nondeterminism

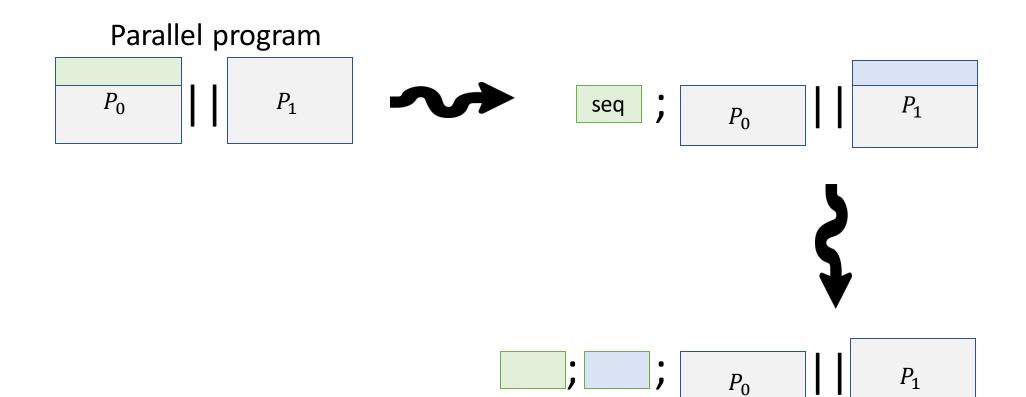
We show how *sequentialization* works for

Probabilistic choiceCastingConditional Communicationx = y [p] zx = (float32) ycond-send(b, tid, type, val)

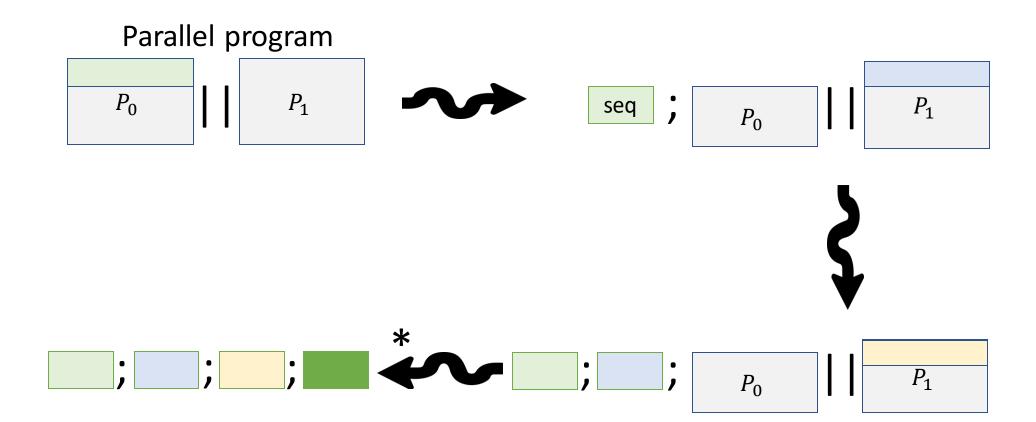
Sequentialization through rewrites



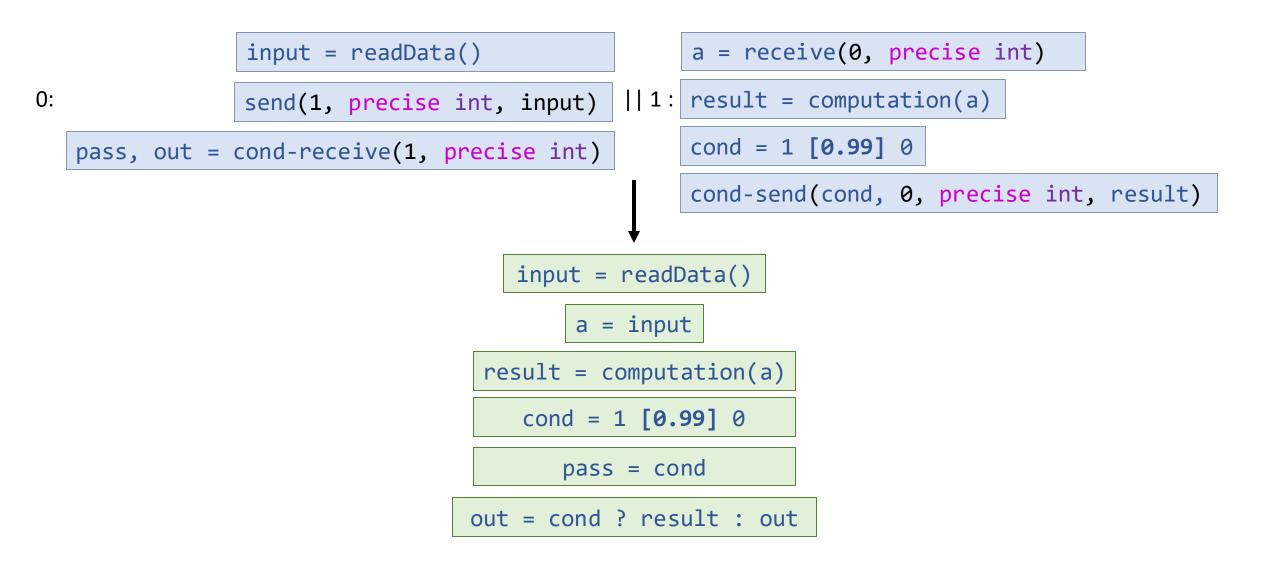
Sequentialization through rewrites

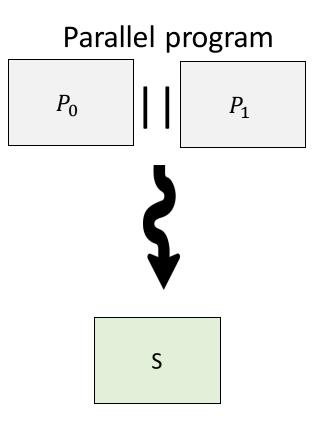


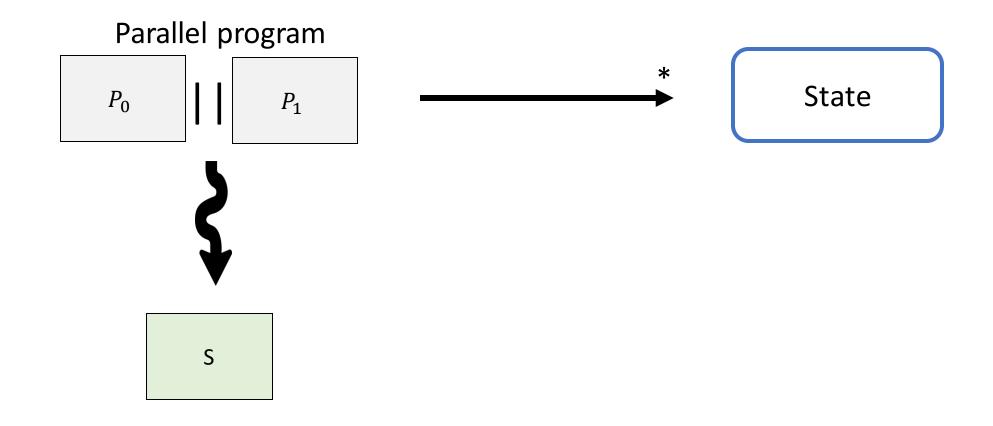
Sequentialization through rewrites

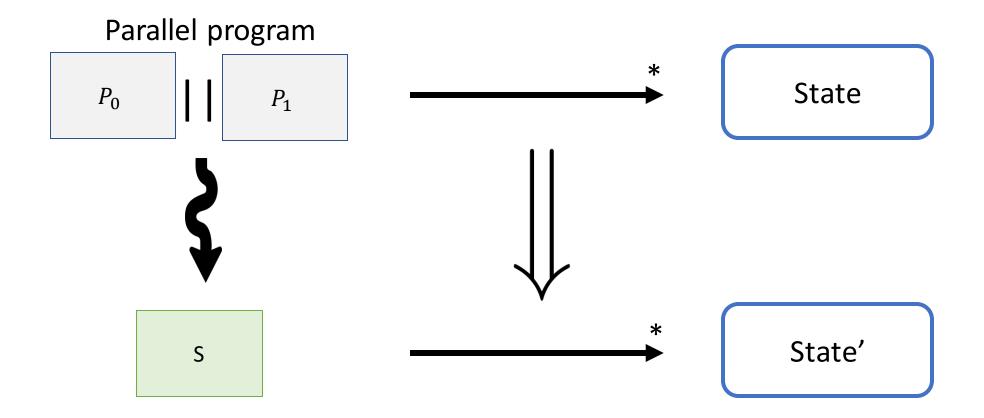


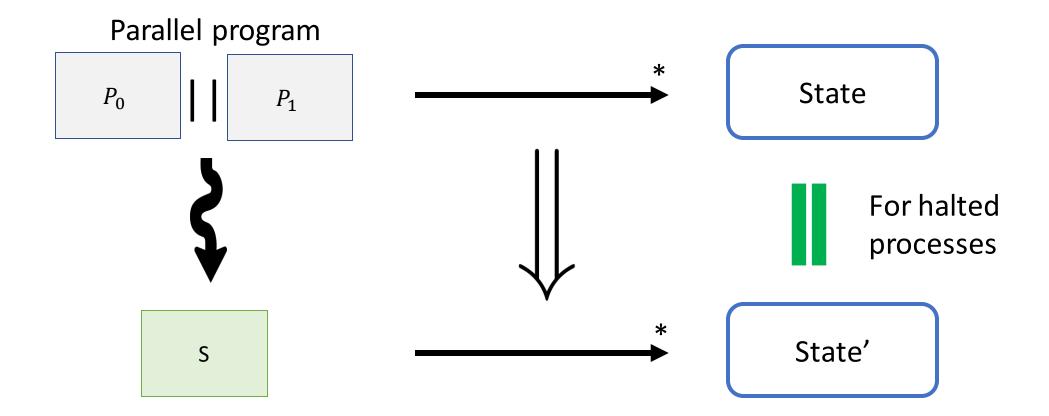
Generating a Canonical Sequentialization





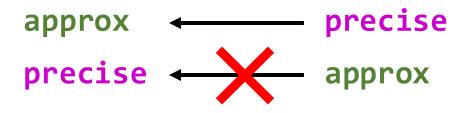






Non-Interference

 Set of type rules that block explicit and implicit flows in each individual process

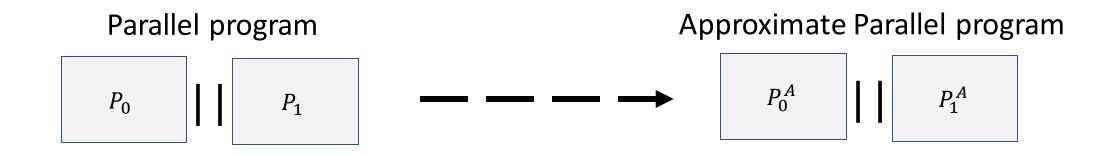


• Typed channels and sequentialization detects illegal flows across process boundaries

0: send(1, approx int, result)

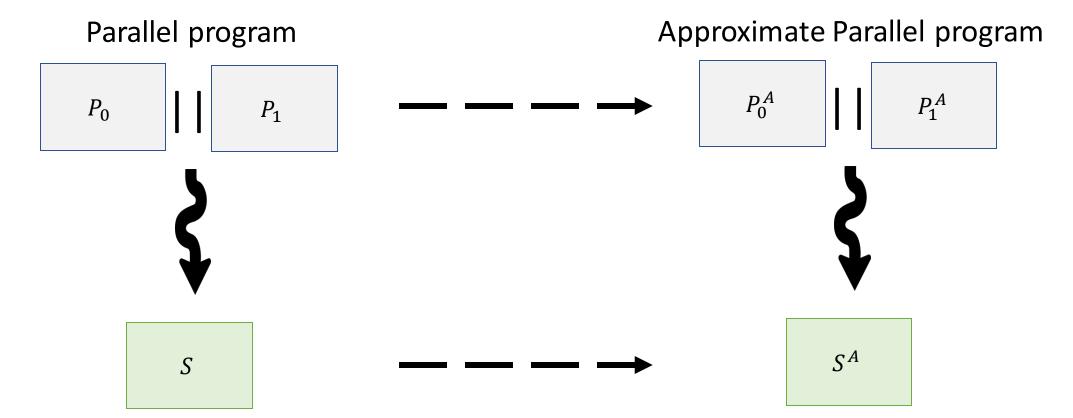
1: out = receive(0, precise int)

Relative Safety

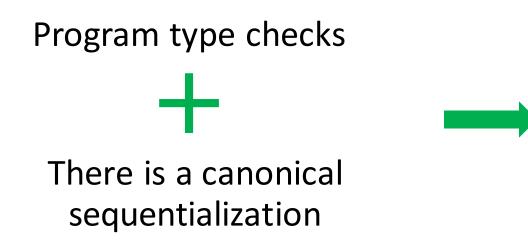


If the original program satisfies a property, then the transformed program also satisfies that property

Relative Safety



We can use the sequentialized programs to prove relative safety for process local safety property



No Deadlocks (Bakst et al. OOPSLA 2017)

Non-interference

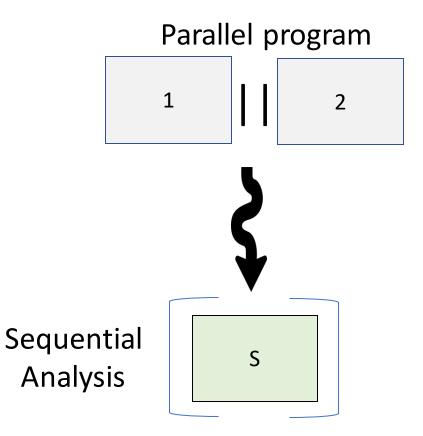
Relative safety

Reliability/Accuracy analysis

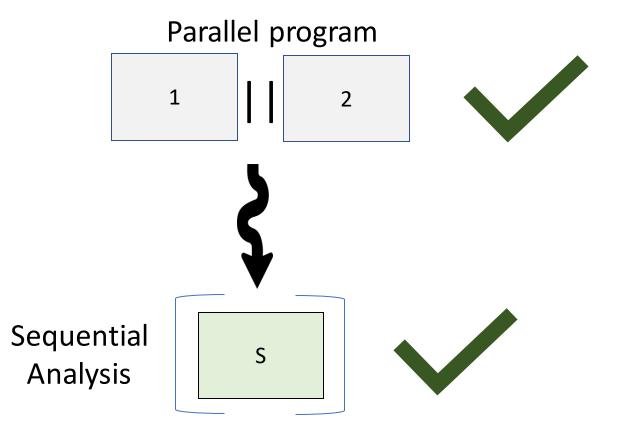
Reliability – Probability that an approximate execution produces the same result as an exact one

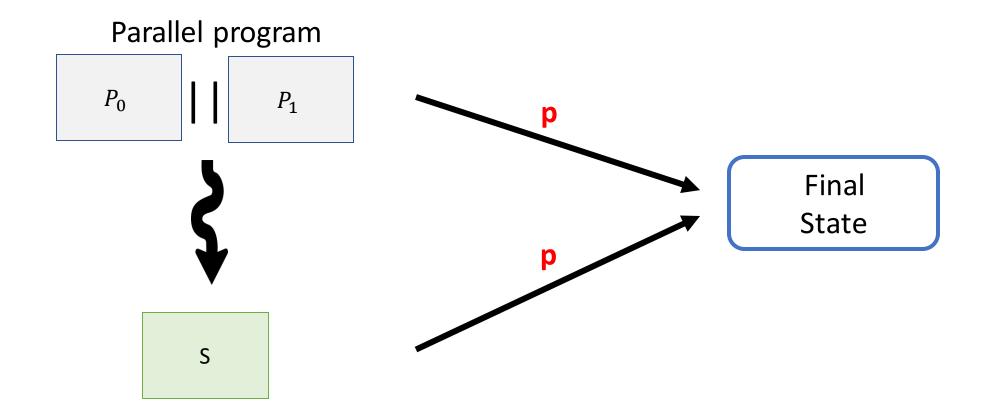
Accuracy – Probability that an approximate execution produces a result close to an exact one

Reliability/Accuracy analysis

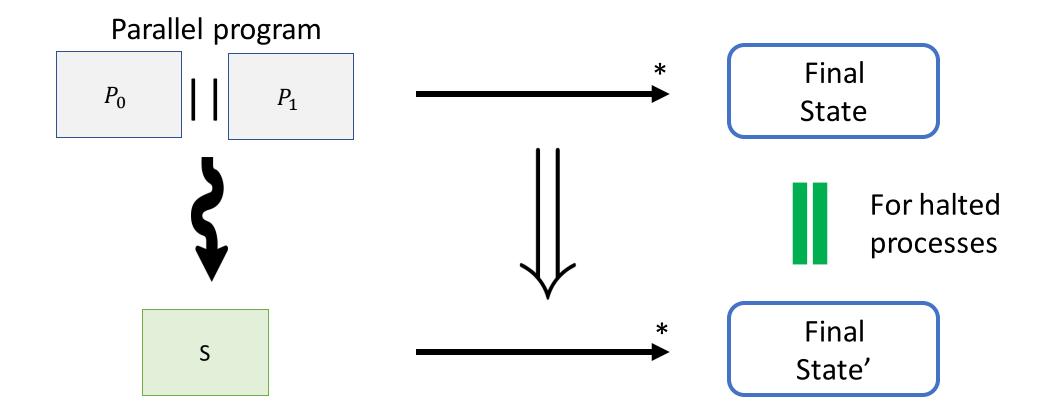


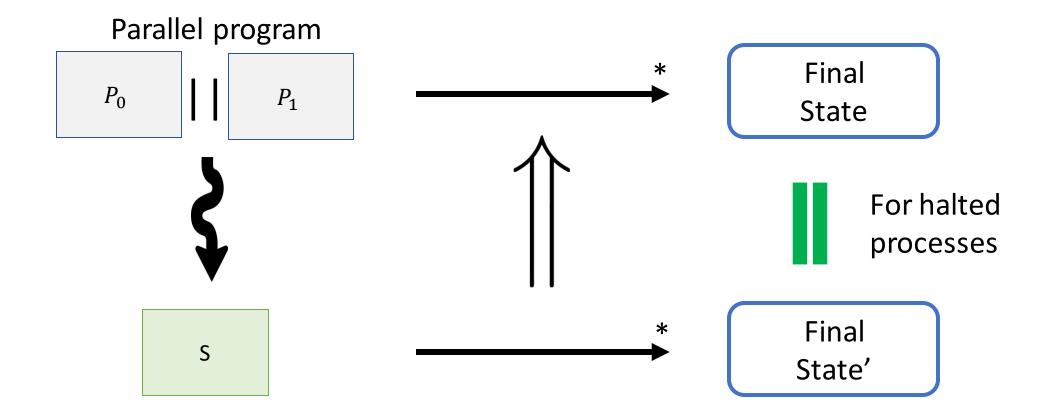
Reliability/Accuracy analysis

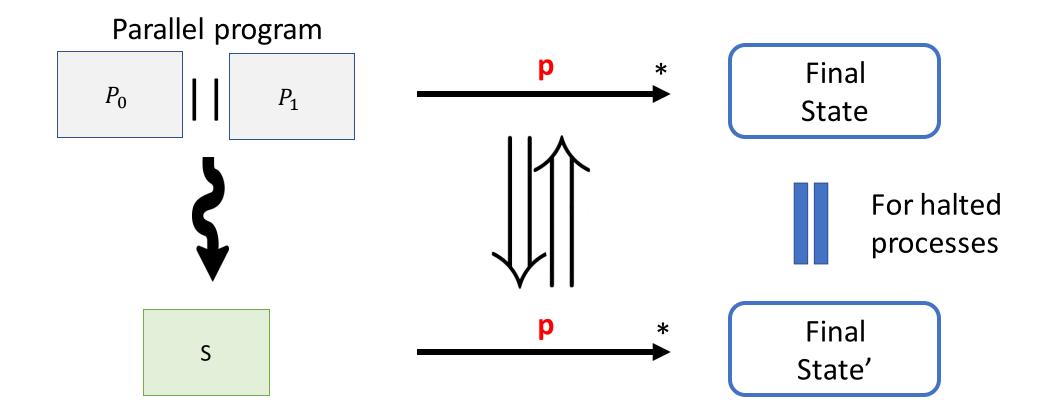


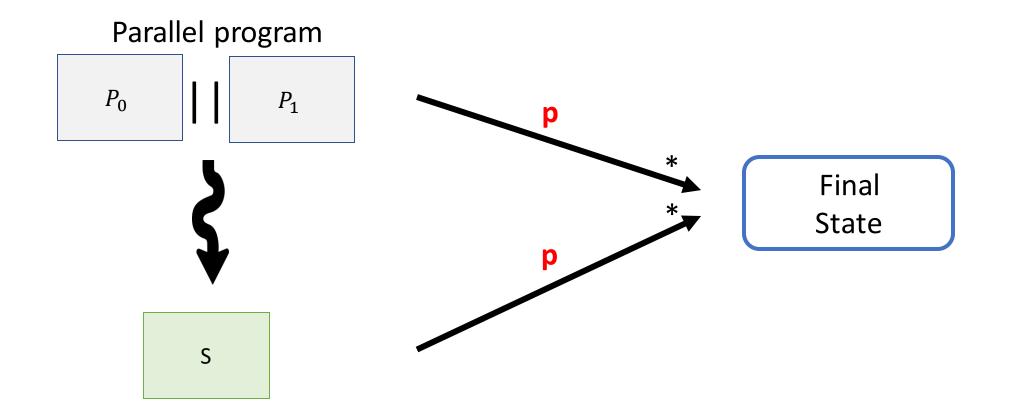


Rewrite Soundness



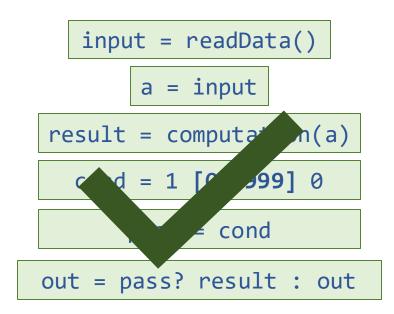




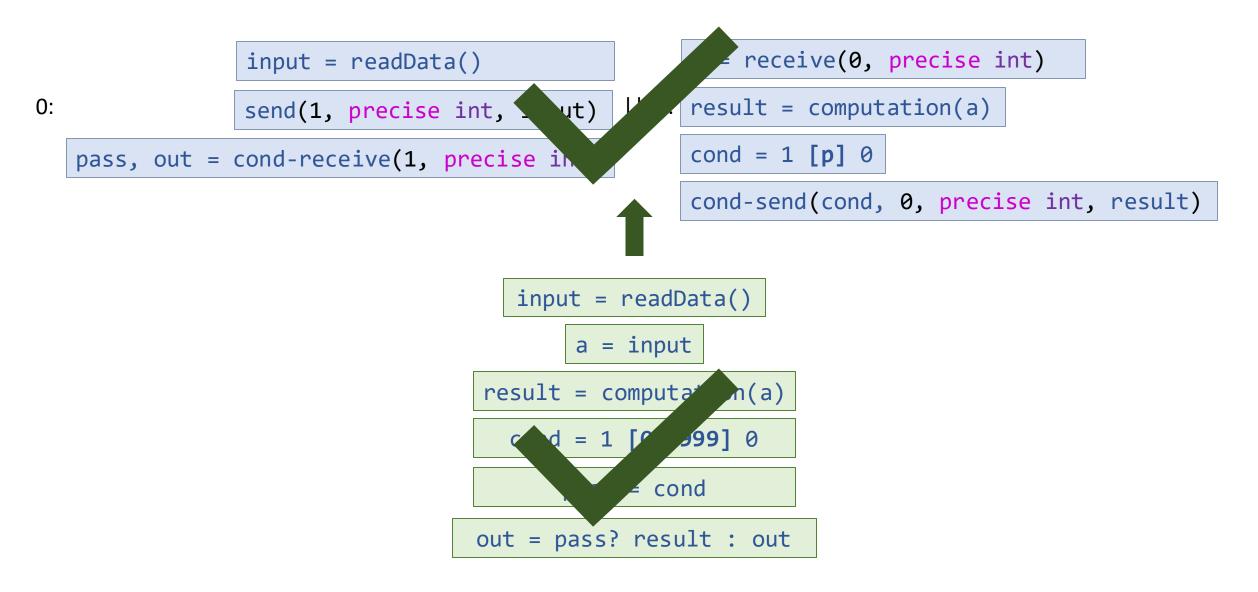


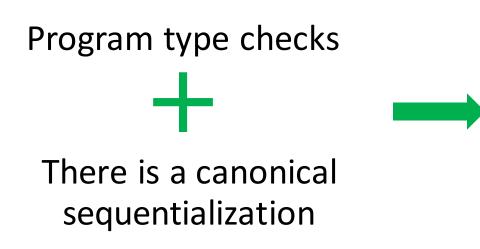
Reliability Analysis (Rely – Carbin et al. 2013)

$0.99 \leq R(out)$



Reliability Analysis





No Deadlocks

Non-interference

Relative safety

Reliability and accuracy analysis on the sequential program valid on the parallel

Evaluation - Benchmarks

Benchmark	Parallel Pattern	Approximation
PageRank	Мар	Failing Tasks
Scale	Мар	Failing Tasks
Blackscholes	Мар	Noisy Channel
SSSP	Scatter-Gather	Noisy Channel
BFS	Scatter-Gather	Noisy Channel
SOR	Stencil	Precision Reduction
Motion	Map/Reduce	Approximate Reduce
Sobel	Stencil	Precision Reduction

Benchmarks – Verification Time

Time

Benchmark	Approximation	Property	Type + Seq	Rel / Acc
PageRank	Failing Tasks	Safety + Reliability (0.99)	1.8s	168s
Scale	Failing Tasks	Safety + Reliability (0.99)	6.5s	7.4s
Blackscholes	Noisy Channel	Safety + Reliability (0.99)	0.2s	12s
SSSP	Noisy Channel	Safety + Reliability (0.99)	9.6s	9.6s
BFS	Noisy Channel	Safety + Reliability (0.99)	8.9s	9.2s
SOR	Precision Reduction	Safety + Accuracy bound (10 ⁻⁶)	8.3s	53s
Motion	Approx Reduce	Safety	3.9s	-
Sobel	Precision Reduction	Safety + Accuracy bound (10 ⁻⁶)	0.2s	72s

Also in the paper

• Evaluation of the benefits of approximations

• Type System and Proof for non-interference

• Soundness Proofs for reliability and accuracy analysis

New Directions

• Generalizing to verification of other properties – fairness

• Dynamic analysis – proving correctness of runtime systems

• Other parallel models – shared memory, etc



• Parallely is a language that can express many common approximation patterns through three simple approximation primitives

• Parallely leverages canonical sequentialization to extend many existing and future analyses from sequential to parallel programs

• Efficiently verifies safety and accuracy of 8 kernels and 8 popular approximate computing benchmarks